NEXT SNOOP PREDICTOR
IN A HOST CONTROLLER

By:

Phillip M. Jones
Paul B. Rawlins
Kenneth T. Chin

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CROSS REFERENCE TO RELATED APPLICATIONS

The following commonly owned application is hereby incorporated by reference for all

5   purposes:

United States Patent Application Serial No. _____, filed concurrently herewith, entitled

"Efficient Snoop Filter in a Multi-Processor-Bus System" by Paul Rawlins and Phil Jones.

BACKGROUND OF THE INVENTION

1.   **Field Of The Invention**

This invention relates generally to memory systems with multiple processors and

multiple processor buses and, more particularly, to a technique for reducing the cycle time of

processing requests through a memory system.

2.   **Description Of The Related Art**

This section is intended to introduce the reader to various aspects of art which may be

20   related to various aspects of the present invention which are described and/or claimed below.

This discussion is believed to be helpful in providing the reader with background information to

facilitate a better understanding of the various aspects of the present invention. Accordingly, it

should be understood that these statements are to be read in this light, and not as admissions of

prior art.

5   The use of computers has increased dramatically over the past few decades. In years past, computers were relatively few in number and primarily used as scientific tools. However, with the advent of standardized architectures and operating systems, computers soon became virtually indispensable tools for a wide variety of business applications. Perhaps even more significantly, in the past ten to fifteen years with the advent of relatively simple user interfaces and ever increasing processing capabilities, computers have now found their way into many homes.

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The types of computer systems have similarly evolved over time. For example, early scientific computers were typically stand alone systems designed to carry out relatively specific tasks and required relatively knowledgeable users. As computer systems evolved into the business arena, mainframe computers emerged. In mainframe systems, users utilized "dumb" terminals to

15   provide input to and to receive output from the mainframe computer while all processing was done centrally by the mainframe computer. As users desired more autonomy in their choice of computing services, personal computers evolved to provide processing capability on each users desktop. More recently, personal computers have given rise to relatively powerful computers called servers. Servers are typically multi-processor computers that couple numerous personal

20   computers together in a network. In addition, these powerful servers are also finding applications in various other capacities, such as in the communications and Internet industries.

Computers today, such as the personal computers and servers discussed above, rely on

microprocessors, associated chip sets, and memory chips to perform most of their processing

functions. Because these devices are integrated circuits formed on semiconducting substrates, the

technological improvements of these devices have essentially kept pace with one another over the

5   years. In contrast to the dramatic improvements of the processing portions of the computer system,

the mass storage portion of the computer system has experienced only modest growth in speed and

reliability. As a result, computer systems failed to capitalize fully on the increased speed of the

improving processing systems due to the dramatically inferior capabilities of the mass data storage

devices coupled to the systems.

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There are a variety of different memory devices available for use in microprocessor-based

systems. The type of memory device chosen for a specific function within a microprocessor-based

system generally depends upon which features of the memory are best suited to perform the

particular function. There is often a tradeoff between speed and cost of memory devices. Memory

15   manufacturers provide an array of innovative, fast memory chips for various applications.

Dynamic Random Access Memory (DRAM) devices are generally used for main memory in

computer systems because they are relatively inexpensive. When higher data rates are necessary,

Static Random Access Memory (SRAM) devices may be incorporated at a higher cost. To strike a

balance between speed and cost, computer systems are often configured with cache memory.

20   Cache memory is a special high-speed storage mechanism which may be provided as a reserved

section of the main memory or as an independent high-speed storage device. A memory cache is a

portion of the memory which is made of the high speed SRAM rather than the slower and cheaper

DRAM which is used for the remainder of the main memory. Memory caching is effective since

most computer systems implement the same programs and request access to the same data or

instructions repeatedly. By storing frequently accessed data and instructions in the SRAM, the

system can minimize its access to the slower DRAM.

5   Some memory caches are built into the architecture of the microprocessor themselves, such

as the Intel 80486 microprocessor and the Pentium processor. These internal caches are often

called level 1 (L1) caches. However, most modern computer systems also include external cache

memory or level 2 (L2) caches. These external caches are located between the central processing

unit (CPU) and the DRAM. Thus, the L2 cache is a separate chip residing externally with respect

10   to the microprocessor. However, despite the apparent discontinuity in nomenclature, more and

more microprocessors are incorporating larger caches into their architecture and referring to these

internal caches as L2 caches. Regardless of the term used to describe the memory cache, the

memory cache is simply an area of memory which is made of Static RAM to facilitate rapid access

to frequently used information.

Because frequently accessed data may be stored in the cache memory area of main memory,

the portion of the system which is accessing the main memory should be able to identify what area

of main memory (cache or non-cache DRAM) it must access to retrieve the required information.

A "tag RAM" is an area in the cache that identifies which data from the main memory is currently

20   stored in each cache line. The actual data is stored in a different part of the cache, called the data

store. The values stored in the tag RAM determine whether the actual data can be retrieved quickly

from the cache or if the requesting device will have to access the slower DRAM portion of the main

memory. The size of the data store determines how much data the cache can hold at any one time,

and the size of the tag RAM determines what range of main memory can be cached. Many

computer systems, for example, are configured with a 256k cache and tag RAM that is 8 bits wide.

This is sufficient for caching up to 64 MB of main memory.

5   In a multi-processor system, each processor may have access to the primary area of main

memory, with each processor reserving a separate portion for its cache memory. The process of

managing the caches in a multi-processor system is complex. "Cache coherence" refers to a

protocol for managing the caches of a multi-processor system so that no data is lost or over-written

before the data is transferred from a cache to a requesting or target device. Each processor may

10   have its own memory cache that is separate from a larger shared RAM that the individual

processors will access. When these multi-processors with separate caches share a common

memory, it is beneficial to keep the caches in a state of coherence by insuring that any shared

operand that has changed in any cache is changed throughout the entire system.

15   Cache coherency is generally maintained through either a directory based or a snooping

system. In a directory based system, the data being shared is placed in a common directory that

maintains the coherence between the caches. The directory acts as a filter through which the

processor must ask permission to load an entry from the primary memory into its cache. When an

entry is changed, the directory either updates or invalidates the other caches with that entry.

20   Disadvantageously, directory based coherency systems add to the cycle time (previously reduced

by the implementation of cache memory) by requiring that each access to the cache memory go

through the common directory. In typical snooping systems, all caches on a bus monitor (or snoop)

the bus to determine if they have a copy of the block of data that is requested on the bus. Every cache has a copy of the sharing status of every block of physical memory it has.

5   Cache coherency is further exacerbated, however, when the computer system includes multiple processor buses. In a multi-bus shared memory system, a host controller maintains memory coherency throughout all of the processor caches. When a request is received by the host controller in a multi-bus architecture, the host controller snoops adjacent buses and performs associated coherency operations. Disadvantageously, these coherency operations often add cycle time to the processing of the requests to the memory. Any delays in processing the requests

10   minimizes the effectiveness and is contrary to the purpose of incorporating cache memory into system RAMs which is to reduce the cycle time of the requests.

The present invention may be directed to one or more of the problems set forth above.

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BRIEF DESCRIPTION OF THE DRAWINGS

The foregoing and other advantages of the invention will become apparent upon reading the following detailed description and upon reference to the drawings in which:

20   Fig. 1 is a block diagram illustrating an exemplary computer system having a multi-processor-bus architecture;

Fig. 2 is a block diagram illustrating a coherency control module for a computer system

having a multi-processor-bus architecture; and

Fig. 3 is a flow chart illustrating the coherency control associated with a request in

5   accordance with the present technique.

DETAILED DESCRIPTION OF SPECIFIC EMBODIMENTS

One or more specific embodiments of the present invention will be described below. In

10   an effort to provide a concise description of these embodiments, not all features of an actual

implementation are described in the specification. It should be appreciated that in the

development of any such actual implementation, as in any engineering or design project,

numerous implementation-specific decisions must be made to achieve the developers' specific

goals, such as compliance with system-related and business-related constraints, which may vary

15   from one implementation to another. Moreover, it should be appreciated that such a

development effort might be complex and time consuming, but would nevertheless be a routine

undertaking of design, fabrication, and manufacture for those of ordinary skill having the benefit

of this disclosure.

20   Turning now to the drawings and referring initially to Fig. 1, a block diagram of an

exemplary multi-processor-bus computer system is illustrated and designated generally as

reference numeral 10. The computer system 10 typically includes one or more processors or

CPUs. In the exemplary embodiment, the system 10 utilizes eight CPUs 12A-12H. The system

10 utilizes a split bus configuration in which the CPUs 12A-12D are coupled to a first bus 14A,

whereas the CPUs 12E-12H are coupled to a second bus 14B. It should be understood that the

processor or CPUs 12A-12H may be of any suitable type, such as a microprocessor available

from Intel, AMD, or Motorola, for example. Furthermore, any suitable bus arrangement may be

5   coupled to the CPUs 12A-12H, such as a single bus, a split bus (as illustrated), or individual

buses. By way of example, the exemplary system 10 may utilize Intel Pentium III processors and

the buses 14A and 14B may operate at 100/133 MHz.

Each of the buses 14A and 14B is coupled to a chip set which includes a host controller

10   16 and a data controller 18. In this embodiment, the data controller 18 is effectively a data cross

bar slave device controlled by the host controller 16. Therefore, these chips may be referred to

together as the host/data controller 16,18. The host/data controller 16,18 is further coupled to

main memory via one or more memory controllers. In this particular example, the host/data

controller 16,18 is coupled to five memory controllers 20A-20E via five individual bus segments

15   22A-22E, respectively. Each of the memory controllers 20A-20E is further coupled to a segment

of main memory designated as 24A-24E, respectively. As discussed in detail below, each of the

memory segments or modules 24A-24E is typically comprised of dual inline memory modules

(DIMMs). Further, each memory module 24A-24E and respective memory controller 20A-20E

may comprise a single memory cartridge 25A-25E which may be removable. In the present

20   configuration, data may be stored in a "4+1" parity striping pattern wherein one of the memory

cartridges 25A-25E is used to provide redundancy for the collective memory system 26.

The host/data controller 16,18 is typically coupled to one or more bridges 28A-28C via

an input/output (I/O) bus 27. The bridges 28A-28C may be any of a variety of suitable types,

such as PCI, PCI-X, EISA, AGP, etc. The opposite side of each bridge 28A-28C is coupled to a

respective bus 30A-30C. A plurality of peripheral devices 32A and 32B, 34A and 34B, and 36A

5   and 36B may be coupled to the respective buses 30A, 30B, and 30C.

As previously discussed, each CPU 12A-12H may include a segment of cache memory

for storing frequently accessed data and programs. Maintaining coherency among the plurality

of caches in the CPUs 12A-12H is important to the efficient operation of the system 10.

10   Maintaining coherency between the caches found in each CPU 12A-12H is further complicated

by the split bus configuration since coherency should be maintained between the separate buses.

Also, because requests may originate from or be directed to not only one of the CPUs 12A-12H

but also from one of the peripheral devices 32A-32B, 34A-34B, or 36A-36B, cache coherency

should be maintained along the I/O bus 27, as well. To maintain coherency, a mechanism is

15   provided in the host controller 16 to facilitate efficient snooping of the buses in the present multi-

processor-bus system 10, as discussed below.

The host controller 16 typically includes a processor controller (PCON) for each of the

processor and I/O buses 14A, 14B, and 27, as illustrated in Figure 2. For simplicity, the

20   processor controller corresponding to the processor bus 14A is designated as "PCON0," the

processor controller corresponding to the processor bus 14B is designated as "PCON1," and the

processor controller corresponding to the I/O bus 27 is designated as "PCON2." Essentially,

each processor controller PCON0–PCON2 serves the same function, which is to connect a

respective bus that is external to the host controller 16 (i.e., processor bus 14A and 14B and I/O

bus 27) to the internal blocks of the host controller 16. Thus, the processor controllers PCON0-

PCON2 provide the interfaces between the buses 14A, 14B, and 27 and the host controller 16.

5   Fig. 2 illustrates a block diagram of a coherency control module (and associated system

architecture) which may be used in accordance with the present techniques to efficiently manage

the snooping process and maintain cache coherency. The coherency control module 40 functions

as a snoop filter to minimize the number of snoop cycles required to obtain cache coherency. In

the present embodiment, the coherency control module 40 resides within the host controller 16.

10   Alternatively, the coherency control module 40 may reside within the data controller 18 or

possibly in an external device which is coupled to each of the processor buses 14A and 14B and

the I/O bus 27.

          As previously discussed, each processor controller PCON0-PCON2 provides an interface

15   between the coherency control module 40 and a respective bus. For each processor controller

PCON0-PCON2, a corresponding request module 42A, 42B, and 42C is provided within the

coherency control module 40. The request modules 42A-42C are responsible for interaction

within a corresponding processor controller PCON0-PCON2. Further, arbitration elements, such

as multiplexors (not shown) may be used to provide arbitration among the respective request

20   modules 42A-42C. The arbitration elements are included in the generalized reference to the

request module 42A-42C. Each request module 42A-42C accepts the cycle requests (READ or

WRITE) from its respective processor controller PCON0, PCON1, and PCON2 and schedules

the cycles to run through the tag RAM 44. The tag RAM 44 identifies which data from the main

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memory 26 is currently stored in the processor caches associated with each bus segment. The tag

RAM 44 is described further below. Generally, each request module 42A-42C maintains proper

request order, prioritizes the input, and establishes each of the request queues or list structures

within the coherency control module 40. The request modules 42A-42C insure memory

5   coherency through proper cycle order, arbitrate access to the memory among the processor and

I/O buses 14A, 14B, and 27, and optimally utilize the tag look up bandwidth.

Each request module 42A-42C includes a plurality of READ and WRITE request buffers

(not shown). A separate READ and a separate WRITE buffer may be provided for each bus

10   14A, 14B, and 27 in the system, for instance. Each processor controller PCON0-PCON2

monitors a corresponding bus and filters the cycle requests to the coherency control module 40.

The requests from the processor controllers PCON0-PCON2 are stored in the READ and WRITE

buffers until the requests can be processed. Each request module 42A-42C also includes a

plurality of list structures or request queues (not shown) corresponding to the various READ and

15   WRITE buffers. The list structures maintain the proper ordering of requests through the buffers

in the coherency control module 40. Prioritization among the various requests may be arbitrated

through any number of schemes based on user requirements. The particular arbitration scheme

selected and the mechanism for implementing that scheme are inconsequential to the present

invention. The technique described herein can be incorporated in any multi-processor-bus

20   architecture which implements a bus monitoring or snooping system to maintain cache

coherency.

The coherency control module 40 also includes an active snoop queue (ASQ) 46 which may include one or more buffers (not shown) which contain the indices of all requests that are currently active in the coherency control module 40. The indices are used to prevent multiple accesses to the same index simultaneously. In general, the ASQ 46 includes buffers to maintain

5   a list of current cycles that are being processed through the tag RAM interface module 48. The tag RAM interface module 48 provides the interface between the tag RAM 44 and the coherency control module 40 as will be described further below. The ASQ 46 only permits one access per cache line index at a time to maintain proper cycle order and cache state information. In the present embodiment, there is one ASQ 46 for each tag RAM interface module 48. A single ASQ

10   46 and tag RAM interface module 48 are illustrated in Fig. 2. However, it may be advantageous to incorporate more than one ASQ 46 and tag RAM module 48 to provide for even and odd addressing, for instance. In the present embodiment, each ASQ 46 permits sixteen cycles to be active at a time, with each of these cycles being processed independently. Because the ASQ 46 buffers include a fixed number of locations, the number of tag lines that are currently active is

15   limited by the size of the buffers in the ASQ 46.

The tag RAM interface module 48 provides the interface with the tag RAM 44. As previously stated, the tag RAM 44 tracks cachelines stored on each bus segment. In other words, the tag RAM 48 provides a look-up table for data stored in cache memory. The tag RAM

20   interface module 48 may be configured to optimize SRAM access efficiency by implementing a variety of techniques to minimize the number of clock cycles used to switch between READ and WRITE requests, for instance. The tag RAM interface module 46 may also be configured to reduce the number of READ requests to the SRAM whenever possible by interpreting the cache

data based on the cycle characteristics. This may occur if a cycle has a non-cacheable attribute or if the cycle is an explicit writeback. When one of these cycles occur, the tag RAM interface module 48 may switch from a READ mode to a WRITE mode. The tag RAM interface module 48 may also minimize the amount of WRITEs to the SRAM whenever the processor performs a WRITE to an unallocated address. This preserves the address that was allocated prior to the WRITE and alleviates the need to perform an unnecessary cast out of data.

When a request (READ) is received by the host controller 16 in a multi bus segment architecture, such as in the computer system 10, the host controller 16 typically snoops adjacent buses (i.e. the remaining system buses from which the present request did not originate) as required and then searches a posting queue for posted writebacks to the same address. If a posted writeback is detected, it is reordered and expedited to memory and followed by a reread. By forcing the writeback before the READ request is processed, the READ request is assured of returning the most current data. After these operations are complete, the host controller 16 can retire the original request. The challenge is to minimize the time required to perform these coherency operations to minimize the time required to process the request.

The typical method of resolving coherency is to serialize the snoop, writeback search and reread operations, as described above. First the snoop is issued to the bus segment having the address cached. When the snoop results are returned to the host controller 16, the coherency control module searches for posted writebacks with the same address. If a writeback is detected, it is reordered to memory and either snarfed or reread. "Snarfing" generally refers to grabbing a copy of the writeback data from the bus while it is being sent back to memory. A memory

"reread," on the other hand, refers to completing the execution of the writeback to memory and issuing a second read or reread to that address. Snarfing may be more efficient since it does not require an additional step to reread the address. However, snarfing may be disadvantageously more complex to implement than a simple reread. When these operations are complete, the

5   original request is retired. When the coherency operations are serialized in this manner, the cycle execution is delayed and overall system performance is impacted.

The present technique performs the snooping operation in parallel with the posting queue search, the reordering of writeback data to memory and the subsequent reread. This reduces the

10   time to complete the coherency analysis and thereby reduces the cycle time for completing the request. Fig. 3 is a flow chart illustrating the procedure for processing a request through the multi-processor-bus computer system 10 illustrated in Figs. 1 and 2. Fig. 3 should be viewed in conjunction with the continued discussion of Fig. 2 and in conjunction with the following description of the request process.

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Initially, a request (READ) is initiated by a CPU 12A-12H, or some I/O device 32A-32B, 34A-34B, or 36A-36B. By way of example, a READ request to address A ("Request A") is initiated by the CPU 12E, as illustrated in Fig. 2 and as indicated by block 70 of Fig. 3. Request A is received by the host controller 16 via the processor bus 14B. The processor controller

20   PCON1 initiates Request A to both the coherency control module 40 and to the main memory 26, as indicated by blocks 72 and 74 of Fig. 3. Advantageously, by initiating the request to the slower access main memory 26 before analyzing the cached status of the requested data (i.e. checking the cache memory to determine whether the requested data is also stored in the more

easily accessible cache memory), the cycle time for processing the request is minimized even if

the data is not stored in cache memory since the request is immediately initiated to the main

memory 26. If the data corresponding to Request A is found in the cache memory, the request to

the main memory 26 will be cancelled, as explained further below.

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After the processor controller PCON1 initiates Request A, the host controller 16 analyzes

the cached status of the requested data by issuing snoops to the adjacent buses, here the processor

bus 14A and the I/O bus 27, to check if one of the buses 14A or 27 currently has the requested

address (A) cached, as indicated by block 76 of Fig. 3. Each snoop request to address A

10 ("SNOOP A") is delivered from the request module 42A and 42B to a corresponding processor

controller, PCON0 and PCON2, as illustrated in Fig. 2. The snoop request SNOOP A is stored

in an outbound snoop queue ("Q") to await its turn gaining access to the processor bus. The

snoop queue Q is preferably a first in first out (FIFO) queue in which snoop requests, such as

SNOOP A, are processed in the order in which they are received.

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As previously indicated, in typical systems, the coherency module 40 within the host

controller 16 waits until receiving the results of the snoop ("SNOOP A RESULT") before the

original READ request (REQUEST A) can be processed. If the SNOOP A RESULT is clean,

(i.e. the adjacent bus does not have the requested data cached), the host controller 16 searches its

20 posting queues (not shown) for posted writebacks, and only then can the original request be

retired. To expedite this process, a prediction technique is implemented in the present

embodiment. The prediction technique is used to identify the next snoop transaction to be

processed by the request module 42. Because the outbound snoop queues Q are FIFOs, the

snoop requests are processed in a predictable order. Thus, a future snoop transaction can be

predicted. Once the future snoop transaction is identified, the coherency control module 40 will

search the posting queues in the host controller 16 for writebacks to coherently process the

original request, as indicated by block 78 of Fig. 3. If a posted writeback is detected, the posted

5   writeback is reordered and written to the main memory 26 followed by a snarf of writeback data

or a second READ (or reread) of the main memory 26, as indicated by block 80. This insures

that the latest data is returned to the requestor when completing the original READ request.

Using this technique, the snooping request SNOOP A (block 76) is performed in parallel with the

posting queue search (block 78), the reordering of writeback data to the main memory 26 and the

10   subsequent reread (block 80). By placing these operations in parallel, the overall time to process

the original request is reduced.

        If the SNOOP A RESULT finds the address A, the data is taken from the cache memory

and the request sent directly to the main memory 26 by PCON1 (block 74) is cancelled. If the

15   SNOOP A RESULT does not find the address A, the posting queue process described above is

implemented. Thus, a snoop request, such as SNOOP A is delivered to the processor controller

PCON0/ PCON2 and placed in the outbound snoop queue Q. The processor controller PCON0/

PCON2 runs the snoop requests on its corresponding bus 14A/ 27 based on the order of the

snoop queue Q. In accordance with the present technique, the processor controller will return

20   both the immediate snoop request results and the address of the next snoop request that will run.

For example, the outbound snoop queue Q of PCON0 may have two snoop requests (SNOOP C

and SNOOP B) waiting to be run on the processor bus 14A. When SNOOP A is received by the

processor controller PCON0, it is injected into the Q and will be run third, after SNOOP C and

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SNOOP B. Once SNOOP C is run on the processor bus 14A, the processor controller PCON0

will return not only the result of the SNOOP C transaction, but will also return the address

corresponding to the SNOOP B request. By returning the next address that will be snooped, the

coherency control module 40 is able to begin checking the request posting queues in the host

5   controller 16 before the bus is snooped for the corresponding address. This technique for

predicting the next address to be snooped based on the outbound snoop queue Q allows for early

searching of the posting queues and thereby minimizes the overall request processing time.

10   While the invention may be susceptible to various modifications and alternative forms,

specific embodiments have been shown by way of example in the drawings and will be described

in detail herein. However, it should be understood that the invention is not intended to be limited

to the particular forms disclosed. Rather, the invention is to cover all modifications, equivalents

and alternatives falling within the spirit and scope of the invention as defined by the following

15   appended claims.